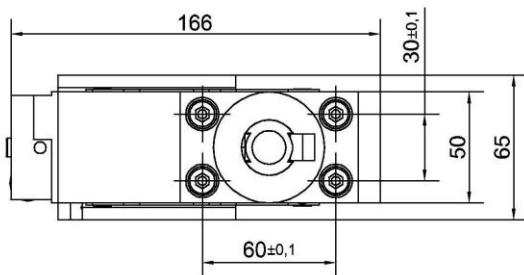
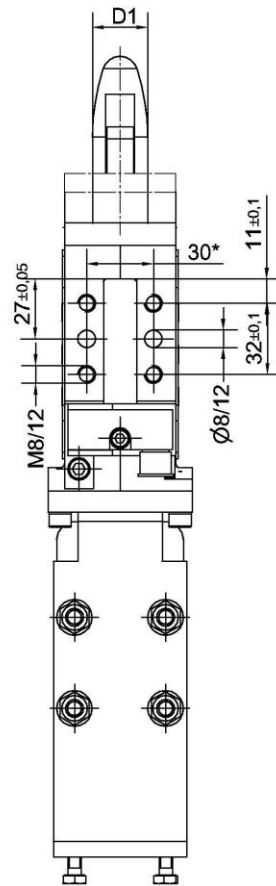
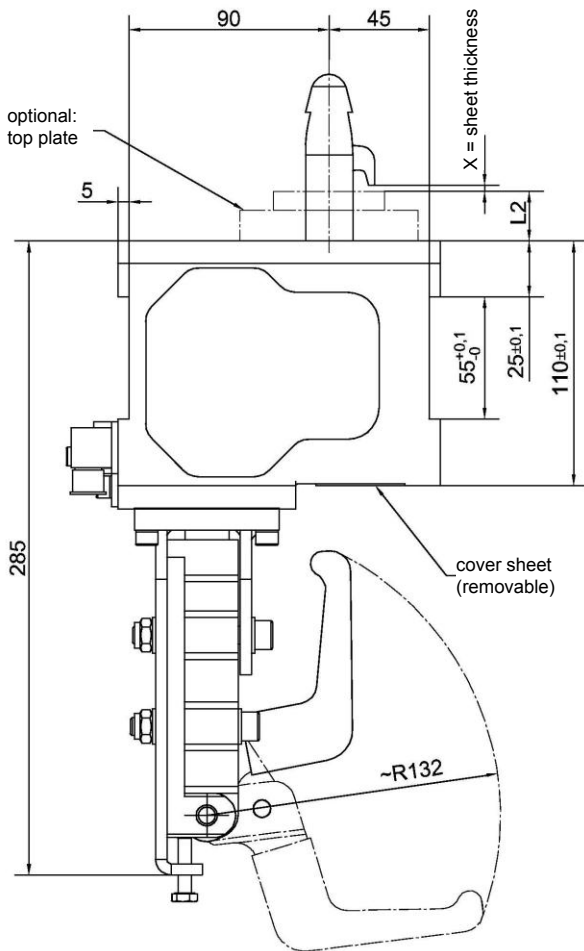


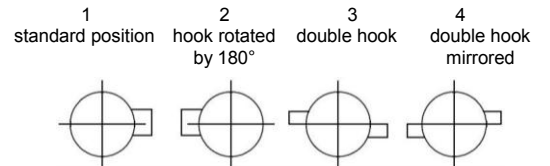
Underbody Clamp

manually operated, for positioning and clamping,
for pin Ø20-40 mm

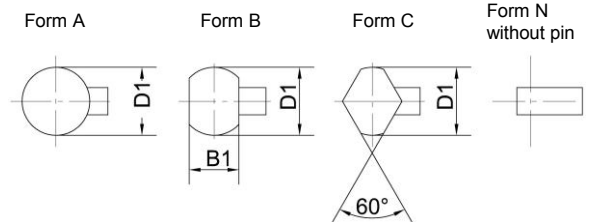
MKN 60 UZ



Hook positions



Pin forms



Example for request:

MKN 60 UZ 1A30_45 T12 X=4.2

MKN 60 UZ:

1: Type
A: Hook position
30: Pin form
45: Pin diameter D1
T12: Height L2
X=4.2: Sensing system
Sheet thickness X

Please send your request example to our design office.

* Tolerance for dowel holes ± 0.02 , for threaded holes ± 0.1 .

After checking your request you will receive an individual article number for the requested Underbody Clamp.

Actual, transferable force (**) depends on pin diameter and geometry of the hook.

Ordering example Tünkers sensing systems:

...T00 Without sensing system
...T12 Inductive sensor 24 V, 1 output with integrated LEDs

Type	Holding force** max.	Clamping force at 6 bar	Weight ~ (kg)	L1	D1 Pin Ø	L2 Height	X Sheet thickness	B1
MKN 60 UZ	3800 N	3300 N		285				